

# Discrete Mathematics and Its Application 2 (CS147)

*Lecture 3: Worst-case asymptotic running time*

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## Target

Analyzing the **runtime** of an **algorithm** for a **computational problem** using **Big-O** notation.

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- ▶ Q1: What is a computational problem?
- ▶ Q2: What is an algorithm?
- ▶ Q3: How to define an algorithm's runtime?

# Computational problem (decision problem)

## Example

**Input** - An array  $A[1, 2, \dots, n]$  of  $n$  numbers.

$\Leftrightarrow A[1], A[2], A[3], \dots, A[n]$

For each  $i \in \{1, 2, \dots, n\}$ ,  $A[i]$  is a real number.

# Computational problem (decision problem)

## Example

**Input** - An array  $A[1, 2, \dots, n]$  of  $n$  numbers.

**Output**

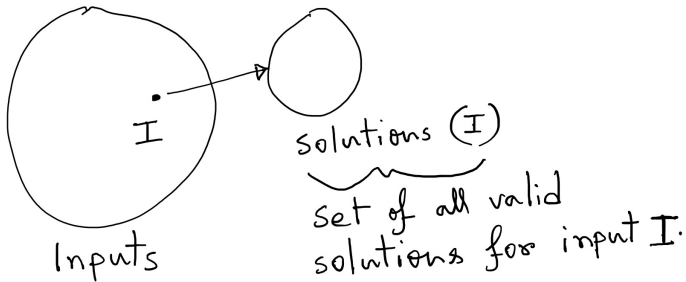
- ▶ Yes if there exist indices  $i, j \in \{1, 2, \dots, n\}$  with  $i \neq j$  such that  $A[i] + A[j] = 0$ .
- ▶ No otherwise.

Computational problem P (say)

- the class of decision problems that are solvable in polynomial time

## Computational problem (decision problem)

In the previous example, for all inputs  $I$ , either  $\text{solutions}(I)=\text{Yes}$  or  $\text{Solutions}(I) = \text{No}$ . A computational problem  $P$  consists of:



- ▶ decision problem: the answer for every input is either yes or no
- ▶ search problem, counting problem, optimization problem...



# Algorithm

## Definition

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- ▶ Input:  $I$
- ▶ Output: A valid solution for  $I$

## An algorithm for our example problem

### An example algorithm (Pseudocode)

```
For  $i = 1, 2, \dots, n$   
  For  $j = i + 1, i + 2, \dots, n$   
    If  $A[i] + A[j] = 0$   
      Return YES.  
Return No.
```

You can **implement** this algorithm by writing a **computer program** in C, C++, Java etc.

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You can **implement** this algorithm by writing a **computer program** in C, C++, Java etc.

```
c/c++  
//Using for-loops to add numbers 1 - 5  
int sum = 0;  
for (int i = 1; i <= 5; ++i) {  
    sum += i;  
}  
  
Python  
for i in range(1, 6): # gives i values from 1 to 5 inclusive (but not 6)  
    # statements  
    print(i)  
# if we want 6 we must do the following  
for i in range(1, 6 + 1): # gives i values from 1 to 6  
    # statements  
    print(i)
```

# Algorithms vs. Programs

- ▶ The same algorithm can be implemented in different programming languages.
- ▶ An algorithm is an abstract mathematical object, independent of
  - the programming language it has been implemented in
  - the machine (computer) it is running on.

# Runtime of an program and algorithm

## Statement

*Runtime of a computer program = the actual time (say, in microseconds) if it takes to finish execution.*

- ▶ It depends on
  - the input
  - the programming language
  - the machine (computer)

## Example: Runtime of an algorithm

### An example algorithm (Pseudocode)

(take  $c_1$  time) **1.** For  $i = 1, 2, \dots, n$   
(take  $c_2$  time) **2.**     For  $j = i + 1, i + 2, \dots, n$   
(take  $c_3$  time) **3.**             If  $A[i] + A[j] = 0$   
(take  $c_4$  time) **4.**                     Return YES.  
(take  $c_5$  time) **5.** Return No.

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Total time spent on an input of size  $n$

$$\leq c_1 n + \sum_{i=1}^n c_2 (n - i) + \sum_{i=1}^n c_3 (n - i) + \sum_{i=1}^n c_4 (n - i) + c_5 = \Theta(n^2)$$

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We will say that the algorithm has a runtime of  $\Theta(n^2)$ .

# Runtime of an algorithm

Formally, let

$$f(n) = \max_{\text{input } I \text{ of size } n} (\text{runtime of the algorithm on input } I)$$

We will focus on how  $f(n)$  grows with input size  $n$ , asymptotically.

⇔ **Worst-case asymptotic running time of an algorithm.**

# Worst-case asymptotic running time

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- ▶ Is a feature of an algorithm for a given computational problem
- ▶ Independent of
  - programming language
  - specific input
  - machine (computer)
- ▶ Allows us to compare two different algorithms for the same problem.

# Worst-case asymptotic running time

- ▶ An  $\mathcal{O}(n^2)$  time algorithm is better than an  $\mathcal{O}(n^3)$  time algorithm
- ▶ An  $\mathcal{O}(n \log n)$  time algorithm is better than an  $\mathcal{O}(n^2)$  time algorithm

## Goal

Given a computational problem, our goal will be to find an algorithm for it with smallest possible worst-case asymptotic runtime.

# Runtime of an algorithm

## Statement

- ▶ *constant time  $\mathcal{O}(1)$ : arithmetic/logic operation, access one element in an array*
- ▶ *linear time  $\mathcal{O}(n)$ : merge two sorted arrays ([Lecture 5](#))*
- ▶ *quadratic time  $\mathcal{O}(n^2)$ : bubble sort ([Lecture 4](#))*
- ▶ *logarithmic time  $\mathcal{O}(\log n)$ : binary search ([Lecture 6](#))*
- ▶ *linearithmic time  $\mathcal{O}(n \log n)$ : merge sort ([Lecture 5](#))*

## Beyond the worst case runtime analysis

- ▶ the best case: find one input that the algorithm can perform the best
- ▶ the average case: **averaged** over all possible inputs for *randomized* algorithm
- ▶ runtime analysis vs. memory analysis



## \*Examples in TCS, ML theory

**Theorem 6** (arbitrary loss). *From random initialization, with probability at least  $1 - e^{-\Omega(\log^2 m)}$ , gradient descent with appropriate learning rate satisfy the following.*

- If  $f$  is nonconvex but  $\sigma$ -gradient dominant (a.k.a. Polyak-Lojasiewicz), GD finds  $\varepsilon$ -error minimizer in<sup>14</sup>

$$T = \tilde{O}\left(\frac{\text{poly}(n, L)}{\sigma \delta^2} \cdot \log \frac{1}{\varepsilon}\right) \text{ iterations}$$

as long as  $m \geq \tilde{\Omega}(\text{poly}(n, L, \delta^{-1}) \cdot d\sigma^{-2})$ .

- If  $f$  is convex, then GD finds  $\varepsilon$ -error minimizer in

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as long as  $m \geq \tilde{\Omega}(\text{poly}(n, L, \delta^{-1}) \cdot d \log \varepsilon^{-1})$ .

Figure: time complexity and parameter complexity [AZLS19].

**Corollary 1.3.** *Let  $\mathcal{D}$  be the distribution over pairs  $(x, y) \in \mathbb{R}^d \times \mathbb{R}$  where  $x \sim \mathcal{N}(0, \text{Id})$  and  $y = F(x)$  for a size- $S$  ReLU network  $F$  for which the product of the spectral norms of its weight matrices is a constant.*

*Then there is an algorithm that draws  $N = d \log(1/\delta) \exp(O(k^3/\varepsilon^2 + kS))$  samples, runs in time  $\tilde{O}(d^2 \log(1/\delta)) \exp(O(k^3 S^2/\varepsilon^2 + kS^3))$ , and outputs a ReLU network  $\tilde{F}$  such that  $\mathbb{E}[(y - \tilde{F}(x))^2] \leq \varepsilon$  with probability at least  $1 - \delta$ .*

Figure: Recall the example in Lecture 1: sample complexity and time complexity [CKM22].

# References I

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